

Lecture 6: Cognitive Ontogeny



Cogs 102A * Dr. Christine Johnson

Learning

- In Psychology, Learning has traditionally been seen as the individual's acquisition of knowledge
- In contrast, in DCog...
- **Learning** = Adaptive processes by which learner's behavior is brought into coordination with a task
 - Task demands include engaging with affordances of a cognitive artifact, situation, another person, oneself, etc
 - “Coming into coordination” includes changing how stably & flexibly the learner engages the task
 - Process is largely observable in changes in allocation of attention, affect, object manipulation, vocalization, etc.

Vygotsky

- Russian psychologist (1896-1934)
- Embraced (Marxist) *Dialectic*

- Focused on *social* aspects of development
- “Socio-historical”
(**Cultural**) development





VYGOTSKY

- All higher cognitive functions
“appear twice”
 - First as **inter**-personal
(social, visible)
 - Later as **intra**-personal
(invisible, mental)



Vygotsky

“Zone of Proximal Development”



Vygotsky

“Zone of Proximal Development”

- Child participates, with more proficient others, in some organized practice
- Child comes to make relevant moves, to correctly time & place those moves, eventually to play all roles, etc.
- Zone “spans” distance from what child can do to child's current “potential” with help



Vygotsky

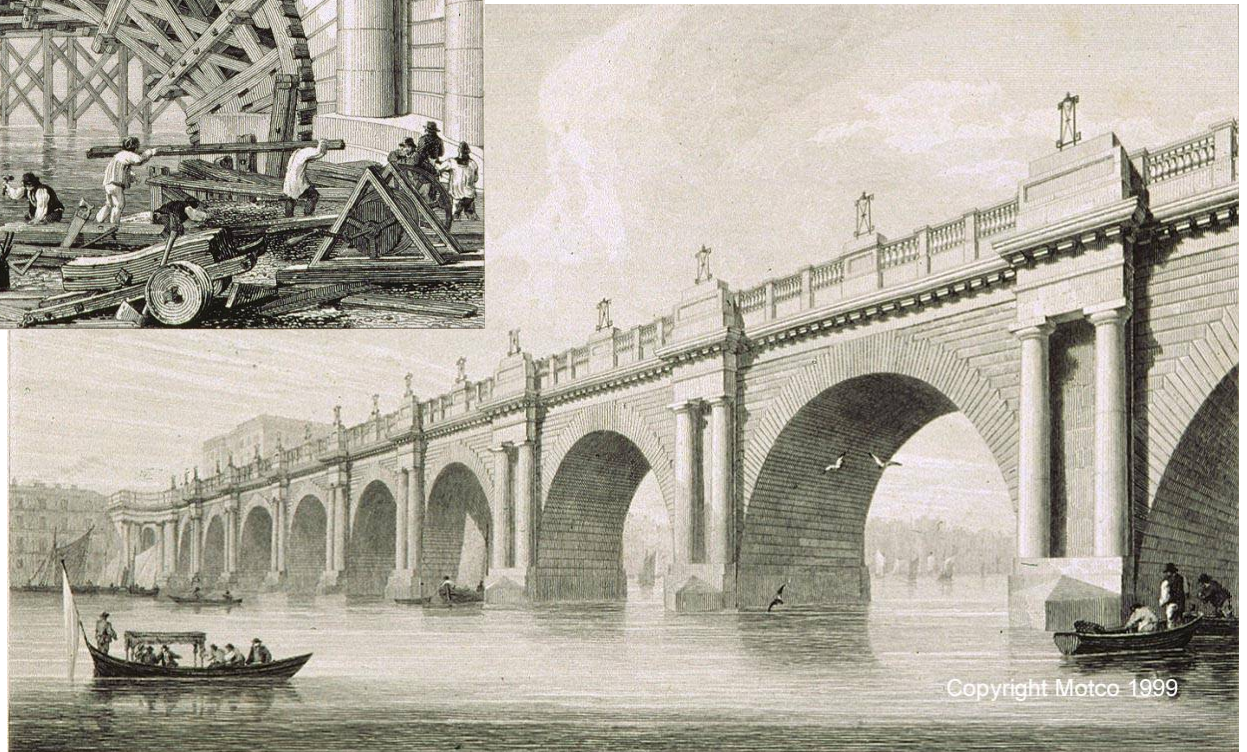
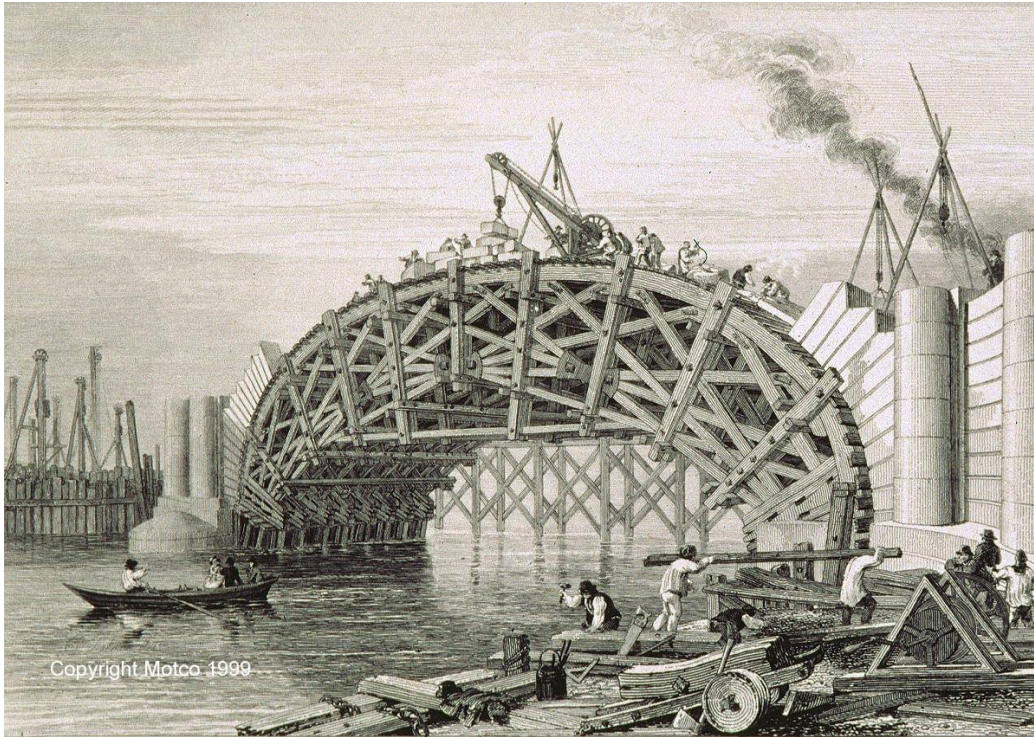
“Zone of Proximal Development”



KEY
to today's
Lab!

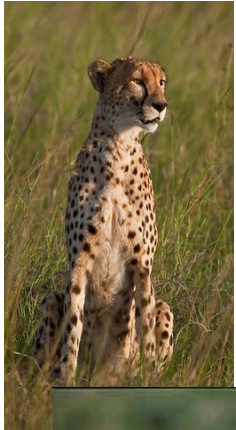
- Methodologically, observe changes in the nature, timing, and proportion of contributions of the participants.

Scaffolding



Scaffolding

- In any **Apprenticeship** - involving children or adults - social learning includes Vygotskian **Scaffolding**



- More proficient “Expert”
(e.g. parent, teacher, practiced peer)
scaffolds “Novice”



Scaffolding

- Applies to any **mediated learning** situation
 - Even when “Expert” is a book (!)
- When Expert is an artifact, Novice plays a more active role in directing attention to affordances



Functions of the **Expert** in Scaffolding

Wood, Bruner & Ross (1976)

- Recruit Novice's interest, via...
 - Drawing in to positive engagement
 - **Highlighting** relevant objects, affordances
- Simplify the task (often into sub-tasks)
 - Challenge, just ahead of Novice proficiency
- Demonstrate idealized version
- Mark critical features of discrepancies
 - e.g. Via imitation & correction
- Maintain pursuit of goal
 - Provide interim payoffs
 - Maintain trust
 - Control frustration, risk



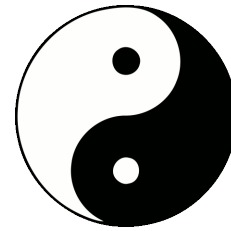
Active Role of Novice

Rogoff (1991)

- Children are *active* participants in Zone, even if role limited
- Child is most frequent initiator of interactions
 - Infant whines, Adult helps, Infant relaxes
 - Infant reach, touch, Adult asks “Want?”
Adult hands object, Infant grasps
 - Child elicits talk, support from others
- If task too easy, Infant bored . . .
 - Will challenge Adult for more elaborate involvement



So, the ZPD is a **Dialectic**



- Expert and Novice create, and adapt to, problem-space changes during learning

Discoveries from Distributed Development

Macro-Level Analysis

Bakeman & Adamson (1984)

“Coordinating Attention to People and Objects in Mother-Infant and Peer-Infant Interaction”





Macro-Level Analysis

Bakeman & Adamson (1984)



METHODS

- Longitudinal study, Infants 6 to 18 months
- Paired with Mom or with Peer
- Free play with objects
- Scored video into macro-level “Engagement States”
 - Infant unengaged
 - Infant onlooking (as other engages with object)
 - Infant engaged with person only
 - Infant engaged with object only
 - Passive Joint (both attend object, but infant not also attend mom)
 - Co-Ord Joint (both attend to object and to each other)



Macro-Level Analysis

Bakeman & Adamson (1984)



RESULTS:

- Mother-Infant dyads (compared to Peers) show...
 - More *Passive Joint* & *Coordinated Joint*
 - Mom more likely (than Peer) to do *Passive Joint* after kid *Onlooking*, or after kid in solitary *Object* play

IMPLICATIONS:

- Mom **scaffolds** infant activity by . . .
 - Watching for infant's relevant state (e.g. *Onlooking* or *Engaged w/obj*)
 - Making object salient (by timing own engagement to coincide w/inf's)
 - Making self available for co-ord (again, by timing own engagement)



Macro-Level Analysis

Bakeman & Adamson (1984)



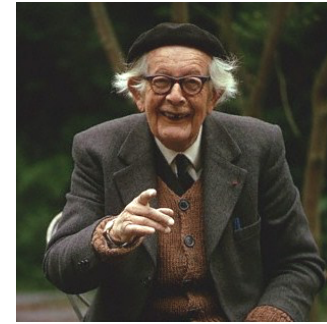
BUT!

- This developmental account is limited to gross transitions in engagement states across the ages
- Does NOT provide info on HOW such changes come about
 - e.g. Via capacity to represent intentions of other?
 - e.g. Via dynamic sensori-motor couplings?
 - Need to actually LOOK at those details . . . (See last lecture!)

Piaget's A-not-B Error

Piaget

Premiere developmental psychologist of 20th century



(1896-1980)

TASK:

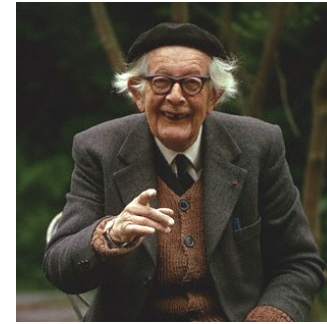
- Repeatedly, as infant watches, hide object under cover **A**



Piaget's A-not-B Error

Piaget

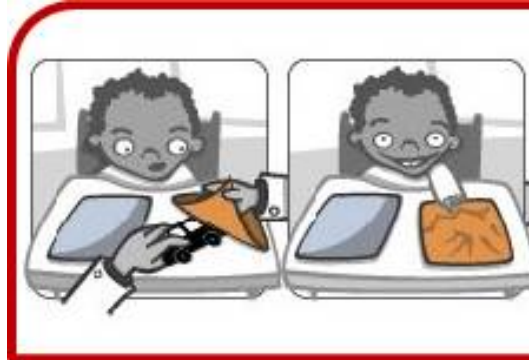
Premiere developmental psychologist of 20th century



(1896-1980)

TASK:

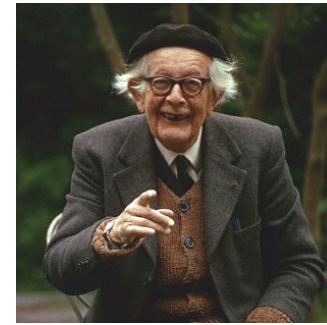
- Repeatedly, as infant watches, hide object under cover **A**
 - Then let infant reach for hidden object



Piaget's A-not-B Error

Piaget

Premiere developmental psychologist of 20th century



(1896-1980)

TASK:

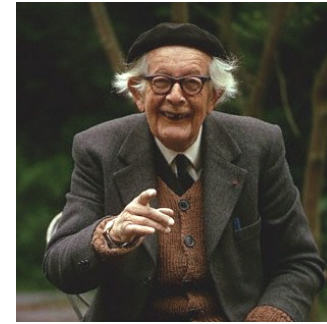
- Repeatedly, as infant watches, hide object under cover **A**
 - Then let infant reach for hidden object
- Then hide under **B** and, after short delay, let infant reach



Piaget's A-not-B Error

Piaget

Premiere developmental psychologist of 20th century



(1896-1980)

TASK:

- Repeatedly, as infant watches, hide object under cover **A**
 - Then let infant reach for hidden object.
- Then hide under **B** and, after short delay, let infant reach



- 8-10 month old infants reach to A (not B!)
 - By 12 months, infant looks & reaches to B.
- **Piaget**: Only 12 months “know” that objects exist & persist.

Smith & Thelen (2003)

Contemporary Vygotskians, on Piaget's (*Vanishing*) **A-not-B Error**

- **BUT** 9 month old acts like 12 month old if...

- Shift posture to standing
- Put on wrist weights
- Highlight hole covers
- Exaggerate hiding event
- Etc!



- So, just as we saw with the issue of asking...

- “Does infant have the ability to crawl?”
- Problematic, since there are MULTIPLE interacting factors (movements, gravity, etc)
- Same is true of performance on A-not-B task!



Smith & Thelen (2003)

Contemporary Vygotskians, on Piaget's (*Vanishing*) **A-not-B Error**

SO:

- ASK not “What does infant *know*?”
- But “Under what conditions do we see stable/unstable performance?”
- And “How do factors interact, change?”
- Also, “What real-world activity improves performance?”
 - e.g. Crawling (Can get to out of sight objects)
 - e.g. Fine motor control (More ways to handle, & therefore see, stuff)



Micro Matters!



- Modern technology
 - Video
 - Motion tracking
 - Eye Tracking
 - Massive datafile processing

- Allows...
 - Multi-modal
 - Moment-to-moment
 - Detailed developmental record



Infants use their heads - to reach!

Shen et al. (2010)



Infants use their heads - to reach!

Shen et al. (2010)

METHODS:

- Subjects 1 ½ to 5 years of age
- Motion sensors on Head & Hands
- Bird's Eye view and Face-on cameras

- Presented with pairs of objects
 - Free to reach



Infants use their heads - to reach!

Shen et al. (2010)



RESULTS:

- All showed Head-stabilization before reach
- Also co-orientation of Head and reaching Hand
- Older looked longer before reach, younger just at reach

IMPLICATIONS:

- Reaching is not just about the hands!
- Instead, about cross-modal sensory-motor coordination

"Gavagai"

The problem of identifying referent

- Classic problem in Linguistics
- Proficient speaker says "Look at the Gavagai!"
- How does learner know to which of myriad aspects of the visual world the speaker is referring???
- Rabbit? Grass? Path? Ears? Eye? Prey? Green? etc. etc. etc.
- Traditional solutions propose conceptual constraints
 - e.g. Innate categories, Perceptual biases, etc
- But new, DCog research shows how actual word learning is also constrained by activity of participants!



Active Information Selection

Yu et al. (2009)

“Feed your head!”



Especially once you
can sit stably

Active Information Selection

Yu et al. (2009)



METHODS

- Subjects 19-23 months & Moms
- Head-Camera on Infant and on Mom
- Plus Bird's Eye camera

- Free play with Mom and 3 same-size toys

- Computer Vision can identify Toys, Hand, Faces

Active Information Selection

Yu et al. (2009)



RESULTS

- Objects grasped by infant *LOOM* in his visual field
- Block his view of other objects
- Thereby increase salience of grasped object

IMPLICATIONS:

- Instead of positing innate *conceptual* constraints required for parsing the noisy input of a cluttered world
- Infant actively segments & thus disambiguates its own input

Bootstrapping Association Learning

Yu & Smith (2010)

Bootstrapping Association Learning

Yu & Smith (2010)



METHODS

- Subjects 14 months & Moms
- Eye Tracker determines Infant's point of focus
- Each trial, simultaneously presented...
 - A spoken nonsense word ("gasser", "manu", "colat", etc.)
 - Two (of 6) visual shapes
 - Word is name of one shape in each pair
- After several trials, determined that name was learned if infant looked longer at the named (vs. unnamed) shape

Bootstrapping Association Learning

Yu & Smith (2010)

RESULTS:

- “*Best Learners*” learned name of 5 or 6 shapes
- “*Poor Learners*” learned name of only 1 or 2 shapes
- As training proceeded, “Best” displayed fewer and longer looks at stimuli

IMPLICATIONS:

- Focused looking reduces ambiguity of input
- Infant BOOTSTRAPS (Scaffolds) his own learning
 - “Positive Feedback” or “Ratchet”
- Improves their own chances of detecting regularity of assoc

“What you *learn* is what you see”

Neural-Net Learning

Yu, Ballard & Aslin (2005)

Mom's multi-modal coordination enables Neural-Nets to learn
name-action associations



FIGURE 1.9 The associate training the computational model is wearing ASL eye tracker, CCD camera, microphone, and position sensors. The computational model thus shares multisensory information like a human language learner. This allows the association of coincident signals in different modalities. (From Yu, Ballard, and Aslin 2005, by permission)

Neural-Net Learning

Yu, Ballard & Aslin (2005)



METHODS:

- Mom only
- Eye tracker, Head-mounted camera, Microphone
- Hand & Body motion trackers
- Vocally describe own actions (e.g. “reading” “writing” “stapling” etc),
“as if to a child” (slow, enunciated)

Neural-Net Learning

Yu, Ballard & Aslin (2005)



RESULTS:

- Neural Net learns image-sound associations
 - i.e. Words for actions
 - When computer shown new videos of same actions . . .
 - Could segment video scene appropriately and
 - Generate correct “word”
 - Based on **time-locked, multi-modal** streams

IMPLICATIONS:

- Directed eye and body movements enabled computer vision system to isolate & track pertinent aspects of scene
- Such multi-modal contingencies also available to human language learners

Grounding Word Learning

Yu, Smith & Pereira (2008, Required)

Vocalizations contingent with sustained hand/eye engagement

>> Learning names of objects



Grounding Word Learning

Yu, Smith & Pereira (2008, Required)



METHODS:

- Subjects 17-20 months with Mom
- Head camera & Head Motion tracker on Infant & Mom
- Plus Bird's Eye camera & Computer Vision analysis of video

- Free play with sets of 3 toys,
- Mom teach names (nonsense words) for novel toys
- Tested later by requesting Infant to give named toy

Grounding Word Learning

Yu, Smith & Pereira (2008, Required)



RESULTS:

- Names learned were NOT most frequently spoken
- Instead, were names for toys that were grasped &/or loomed, w/head-stabilized look at time named
 - i.e. Multi-modal (relevant) input makes learning easier!

IMPLICATIONS:

- Language researchers often assume name learning requires “mind-reading” Mom’s “intentions”
- But may be more about salience that emerge from multi-party, time-locked, co-oriented, multi-modal attention.

LAB 4:

Consider the Scaffolding
(gradual change in participation profile)
that occurs even
between expert and novice adults . . .

LOAD “Scaffolding” Video from Lab Page